

Step 1: $\mathcal{H}_0 = \mathcal{H}$, $\mathcal{Q}_1 = (\mathcal{H}_0)_{\varepsilon/D}$

$\mathcal{M}_1 = \{A \in \mathcal{Q}_1 : A \cap B = \emptyset \ \forall A \neq B \in \mathcal{Q}_1\}$ ← matching

$\mathcal{H}_1: V_1 = V \setminus \boxed{\cup \mathcal{Q}_1} := \{A : A \in \mathcal{Q}_1\}$

$\mathcal{H}_1 = \mathcal{H}_0[V_1]$ ($= \mathcal{H}_0 \setminus \{\text{edges mtg } \cup \mathcal{Q}_1\}$)

▶ why not delete only \mathcal{M}_1 ?

— maybe could, but harder to analyze and waste is affordable (as we'll see; a MP)

L26

ROUGH: $|\mathcal{Q}_1| \approx \frac{\varepsilon}{D} |\mathcal{H}| = \varepsilon n / r$ ε -frac. of goal

$$\mathbb{P}(A \in \mathcal{M}_1) = \frac{\varepsilon}{D} \left(1 - \frac{\varepsilon}{D}\right)^{r(D-1)} \begin{cases} \sim \frac{\varepsilon}{D} e^{-\varepsilon r} \\ = \frac{\varepsilon}{D} (1 - \varepsilon r + O(\varepsilon^2)) \end{cases}$$

implied const doesn't depend on ε

→ typ: $|\mathcal{Q}_1 \setminus \mathcal{M}_1| \approx \varepsilon^2 r |\mathcal{H}| / D = \varepsilon^2 n$ $O(\varepsilon)$ -frac of gain

— $\frac{\varepsilon}{r}$ hope to iterate, e.g.

Step 2: $\mathcal{Q}_2 = (\mathcal{Q}_1)_{\varepsilon/D_1}$ ($\mathcal{M}_2 = \dots$)

$$D_1 = e^{-\varepsilon(r-1)} D$$

MP: whp \mathcal{H}_1 approx D_1 -reg. TBD

whence? $d_1(x) := d_{\mathcal{H}_1}(x)$ (r.v.i) $x \in V$

$\mathbb{E} d_1(x)$? wrong question → (right q. is)

$$\mathbb{E}[d_1(x) | x \in V_1] \stackrel{\text{why?}}{=} (1 - \epsilon/D)^{(r-1)(D-1)} D \sim e^{-\epsilon(r-1)} D = D_1$$

▷ concentration? fix $x \notin$ condition on $\{x \in V_1\}$

$$X_A = \mathbb{1}_{\{A \in \mathcal{H}_1\}} \quad (\rightarrow \mathbb{E}X_A \sim e^{-\epsilon(r-1)} \text{ for } A \ni x)$$

$$X = \sum_{A \ni x} X_A = d_1(x)$$

$$A \neq B \ni x \rightarrow \mathbb{E}X_A X_B = (1 - \epsilon/D)^{2(r-1)(D-1) - b}$$

$$b = |\{C \ni x : C \cap A \neq \emptyset \neq C \cap B\}| \leq (r-1)^2$$

[* \mathcal{H} simple (if codeg's $o(D)$ then $b = o(D)$)]

$$\xrightarrow[\text{(EX)}]{\text{Chap}} \text{ (on } \{x \in V_1\}) \quad d_1(x) \sim D_1 \text{ whp}$$

... and iterate: $\approx \frac{1}{\epsilon} \log \frac{1}{\delta}$ steps

$$\text{deg's in } \mathcal{H}_i \text{ shd be } \approx \underbrace{e^{-\epsilon(r-1)} D}_{\approx \delta^{r-1}} =: D_i = \text{still const}$$

But errors accumulate \rightarrow can we hang on?

▷ one point: deg's only mostly good; e.g., after Step 1

there will (typ.) be vertices \bar{w} deg $\neq D_1$

serious problem for F-R



Actual P.T. $\forall r, \delta > 0 \exists \kappa \exists \gamma > 0 \exists D_0$ s.t.

if $D > D_0$ & $\mathcal{H} \in$

(a) r -uniform, n -d (or *codings* ...)

(1) $|\{x: d_{\mathcal{H}}(x) \neq (1 \pm \delta)D\}| < \delta n$

(2) $\Delta_{\mathcal{H}} < \kappa D$

Then $v(\mathcal{H}) > (1 - \delta)n/r$

• false if $\delta \approx 1/\kappa$ (why?) [in fact (EX) need $\delta \lesssim \delta/\kappa$]

• again, main issue is deterioration of estimates

— not obv. This is okay (e.g. AS: §19 (!))

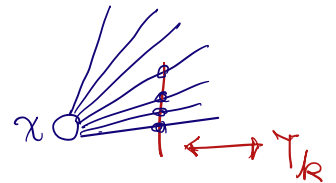
▷ alternative to "ac. Pipp." ($X = d_1(x)$, cond on $\{x \in V_1\}$)

Claim: $\mathbb{P}(|X - \mathbb{E}X| > \delta) < \exp\left[-\frac{\delta^2}{O(\varepsilon D)}\right]$ (why?)
 ↙ think δD

┌ edge exposure mart:

• $|Z_k| \leq r$

• length? $< rD^2 = O(D^2)$ — too big



→ ?

γ_k takes 2 val's, one w prob ε/D

→ "var" $\approx rD^2 \cdot \varepsilon/D \cdot r^2 = O(\varepsilon D)$

⇒ $\exists a, \bar{w}$ no bad verts (why?)
 ↘ $\text{deg} \neq (1 \pm \delta)D_1$

┌ Pf: $\mathbb{P}(x \text{ bad}) = \exp[-\Omega(\delta^2 D/\varepsilon)] + \text{LLL}$

(what are the events?)

▣

cmts

① codeg's $O(D)$: doesn't quite support this arg.

(gives (Ex) $P(|X - EX| > x) = \exp\left[-\frac{x^2}{O(D^2)}\right]$

— so $P(x \text{ bad}) = o(1)$ but not enough for LLL)

but martingales are crucial for more advanced appl's

② first ver: we just watch \nexists show gd behav.

(e.g. most deg's $\approx D_1$) is likely

(N.B. A-S version doesn't quite do this)

second ver: we interfere: show \exists gd increment \nexists
choose one. (\nexists continue)

— Cf. next development (after P's thm):

▷ Pippenger-Spencer '89: P's hypotheses $\Rightarrow \mathcal{X}(x) \sim D$:

• use Pippenger arg to gen. random matchings (M)

\models (e.g.) $P(A \in M) \sim 1/D \quad \forall A \in \mathcal{X}$

• increment ("nibble"): $\leq D$ of these (incept'ly)

▷ Here if we just let the process run (as in PT)

then there will typically (for large n) be underused verts

— \nexists can't catch up

→ must interfere (\rightsquigarrow mart + LLL)