Math 350 - Solutions to review problems for Exam #1 - March 1, 2008 #1 Let V and W be finite dimensional vector spaces and let $T \in \mathcal{L}(V, W)$. Prove that

$$rank(T) + nullity(T) = dim(V).$$

Solution: This is in the text (Theorem 2.3, page 70). Here is a proof. Let $\beta = \{v_1, ..., v_k\}$ be a basis for N(T). Then β can be extended to a basis $\gamma = \{v_1, ..., v_k, v_{k+1}, ..., v_n\}$ of V. Then $\dim V = n$, $\operatorname{nullity}(T) = \dim(N(T)) = k$, and we must show that $\operatorname{rank}(T) = n - k$. Since $\operatorname{rank}(T) = \dim(R(T))$ we can do this by showing that $\alpha = \{T(v_{k+1}), ..., T(v_n)\}$ is a basis for R(T). First we will show that α spans R(T). Let $w \in R(T)$. Then w = T(v) for some $v \in V$. Since $\{v_1, ..., v_n\}$ is a basis for V, we have $v = a_1v_1 + ... + a_nv_n$ for some scalars $a_1, ..., a_n \in F$. Then $w = T(v) = a_1T(v_1) + ... + a_nT(v_n)$. But $v_1, ..., v_k$ are in N(T), so $T(v_1) = ... = T(v_k) = 0$. Thus $w = a_{k+1}T(v_{k+1}) + ... + a_nT(v_n) \in \operatorname{Span}(\alpha)$. Now we show that α is linearly independent. Suppose $0 = b_{k+1}T(v_{k+1}) + ... + b_nT(v_n)$. Then $0 = T(b_{k+1}v_{k+1} + ... + b_nv_n)$ and so $b_{k+1}v_{k+1} + ... + b_nv_n \in N(T)$. Since β is a basis for N(T) this means that

$$b_{k+1}v_{k+1} + \dots + b_nv_n = c_1v_1 + \dots + c_kv_k$$

for some scalars $c_1, ..., c_k \in F$. But then

$$-c_1v_1 - \dots - c_kv_k + b_{k+1}v_{k+1} + \dots + b_nv_n = 0.$$

Since γ is linearly independent, this means that $c_1 = \ldots = c_k = b_{k+1} = \ldots = b_n = 0$. Thus all the b_i are equal to 0. This shows that α is linearly independent and our proof is complete.

#2 Let V be a finite-dimensional vector space over F and let X and Y be subspaces of V. Recall that X + Y denotes $\{x + y | x \in X, y \in Y\}$.

- (a) Show that X + Y is a subspace of V.
- (b) Show that $X \cap Y$ is a subspace of V.
- (c) Prove that

$$dim(X + Y) = dim(X) + dim(Y) - dim(X \cap Y).$$

Solution: (a) Since $0 \in X$ and $0 \in Y$ we have $0 = 0 + 0 \in X + Y$. Now let $u_1, u_2 \in X + Y, a \in F$. Then $u_1 = x_1 + y_1, u_2 = x_2 + y_2$ where $x_1, x_2 \in X, y_1, y_2 \in Y$. Then $u_1 + u_2 = (x_1 + y_1) + (x_2 + y_2) = (x_1 + x_2) + (y_1 + y_2)$. Since $x_1 + x_2 \in X$ and $y_1 + y_2 \in Y$ we have $u_1 + u_2 \in X + Y$. Also $au_1 = a(x_1 + y_1) = (ax_1) + (ay_1)$. Since $ax_1 \in X$ and $ay_1 \in Y$ we have $au_1 \in X + Y$. Thus X + Y is a subspace.

- (b) Since $0 \in X$ and $0 \in Y$ we have $0 \in X \cap Y$. Now let $u_1, u_2 \in X \cap Y$ and $a \in F$. Then $u_1, u_2 \in X$ so $u_1 + u_2 \in X$. Also $u_1, u_2 \in Y$ so $u_1 + u_2 \in Y$. Thus $u_1 + u_2 \in X \cap Y$. Now $au_1 \in X$ and $au_1 \in Y$ so $au_1 \in X \cap Y$. Thus $X \cap Y$ is a subspace.
- (c) Let $\alpha = \{u_1, ..., u_k\}$ be a basis for $X \cap Y$. Then we may extend α to a basis $\beta = \{u_1, ..., u_k, x_1, ..., x_l\}$ of X and we may extend α to a basis $\gamma = \{u_1, ..., u_k, y_1, ..., y_m\}$ of Y. Thus we have $dim(X) + dim(Y) dim(X \cap Y) = (k+l) + (k+m) k = k+l+m$, and so we need to prove that dim(X+Y) = k+l+m. We will verify this by showing that $\delta = \{u_1, ..., u_k, x_1, ..., x_l, y_1, ..., y_m\}$ is a basis for X + Y.

First we show that δ spans X+Y. Let $u \in X+Y$. Then $u=x+y, x \in X, y \in Y$. Then x is a linear combination of elements of β . Thus $x=a_1u_1+...+a_ku_k+b_1x_1+...+b_lx_l$ for some $a_1,...,a_k,b_1,...,b_l \in F$. Similarly y is a linear combination of elements of γ . Thus $y=c_1u_1+...+c_ku_k+d_1y_1+...+d_my_m$ for some $c_1,...,c_k,d_1,...,d_m \in F$. Then $x+y=(a_1+c_1)u_1+...+(a_k+c_k)u_k+b_1x_1+...+b_lx_l+d_1y_1+...+d_my_m \in Span(\delta)$.

Now we show that δ is linearly independent. Suppose there exist elements

$$r_1, ..., r_k, s_1, ..., s_l, t_1, ..., t_m \in F$$

such that

$$r_1u_1 + \dots + r_ku_k + s_1x_1 + \dots + s_lx_l + t_1y_1 + \dots + t_my_m = 0.$$

Then

$$r_1u_1 + \dots + r_ku_k + s_1x_1 + \dots + s_lx_l = -t_1y_1 - \dots - t_my_m$$

Denotote this element by E. Then $E = r_1u_1 + ... + r_ku_k + s_1x_1 + ... + s_lx_l \in X$ and $E = -t_1y_1 - ... - t_my_m \in Y$. Thus $E \in X \cap Y$ and so it is a linear combination of elements of α . Thus

$$z_1u_1 + ... + z_ku_k = -t_1y_1 - ... - t_my_m$$

and so

$$z_1u_1 + \dots + z_ku_k + t_1y_1 + \dots + t_my_m = 0$$

for some $z_1, ..., z_m \in F$. Since γ is linearly independent we have $z_1 = ... = z_k = y_1 = ... = y_m = 0$. But then E = 0 and so

$$r_1u_1 + \dots + r_ku_k + s_1x_1 + \dots + s_lx_l = 0.$$

Since β is linearly independent we have $r_1 = ... = r_k = x_1 = ... = x_l = 0$. This shows that δ is linearly independent and our proof is complete.

#3 Let $\beta = \{1, x, x^2\}$ and $\gamma = \{1, (x+1), (x+1)^2\}$. These are two ordered bases for $P_2(\mathbf{R})$. Let

$$T: P_2(\mathbf{R}) \to P_2(\mathbf{R})$$

be the linear transformation defined by

$$T(f) = xf'.$$

(Here $f = f(x) \in P_2(\mathbf{R})$ and f' denotes the derivative of f.)

- (a) Find $[T]_{\beta}$.
- (b) Find $[T]_{\gamma}$.
- (c) Find the change of basis matrix from β to γ .
- (d) Find the change of basis matrix from γ to β .
- (e) Explain how your answers to (a) (d) are related.
- (f) Find $[T^t]_{\beta^*}$.

Solution: (a) We have
$$T(1) = 0, T(x) = x, T(x^2) = 2x^2$$
. Thus $[T]_{\beta} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$.

Solution: (a) We have
$$T(1)=0, T(x)=x, T(x^2)=2x^2$$
. Thus $[T]_{\beta}=\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$. (b) We have $T(1)=0, T(x+1)=x=-1+(x+1), T((x+1)^2)=2x+2x^2=-2(x+1)+2(x+1)^2$. Thus $[T]_{\gamma}=\begin{bmatrix} 0 & -1 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{bmatrix}$.

(c) This is
$$[I]_{\beta}^{\gamma} = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$
.
(d) This is $[I]_{\gamma}^{\beta} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$.

(d) This is
$$[I]_{\gamma}^{\beta} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

(e)
$$([I]_{\beta}^{\gamma})^{-1} = [I]_{\gamma}^{\beta}$$
 and

$$([I]_{\beta}^{\gamma})^{-1}[T]_{\gamma}[I]_{\beta}^{\gamma} = [T]_{\beta}.$$

(f)
$$[T^t]_{\beta^*} = ([T]_{\beta})^t = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$
.

#4 (a) Is the set of vectors $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$ in \mathbf{R}^3 linearly independent? Why or why not?

(b) Is the vector
$$\begin{bmatrix} 1 \\ -2 \\ 2 \\ 1 \end{bmatrix}$$
 in $Span\{\begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -3 \\ 1 \\ 1 \end{bmatrix}\}$? Why or why not?

(c) Does the set of vectors
$$\left\{\begin{bmatrix} -1\\2\\1\\0\end{bmatrix},\begin{bmatrix} 1\\0\\1\\0\end{bmatrix},\begin{bmatrix} -1\\-1\\1\\1\end{bmatrix},\begin{bmatrix} 1\\1\\1\\2\end{bmatrix}\right\}$$
 span \mathbf{R}^4 ? Why or why not?

Solution: (a) No. A set of 4 vectors in a 3-dimensional vector space cannot be linearly independent.

(b) No. Suppose
$$a_1 \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix} + a_3 \begin{bmatrix} 3 \\ -3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 2 \\ 1 \end{bmatrix}$$
. Then

$$\begin{bmatrix} a_1 + a_2 + 3a_3 \\ a_1 - a_2 - 3a_3 \\ -a_1 + a_3 \\ a_1 + a_2 + a_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 2 \\ 1 \end{bmatrix}.$$

Thus we have the system of equations

$$a_1 + a_2 + 3a_3 = 1$$

$$a_1 - a_2 - 3a_3 = -2$$

$$-a_1 + a_3 = 2$$

$$a_1 + a_2 + a_3 = 1.$$

Subtracting the first equation from the fourth gives $-2a_3 = 0$ and so $a_3 = 0$. Then we have

$$a_1 + a_2 = 1$$

 $a_1 - a_2 = -2$
 $-a_1 = 2$.

Then adding the first and third equations gives $a_2 = 3$ while adding the second and third equations gives $a_2 = 0$. Thus there is no solution, giving the result.

(c) Yes. This set of 4 vectors in the 4-dimensional space \mathbb{R}^4 spans \mathbb{R}^4 if and only if it is linearly independent. If

$$a_1 \begin{bmatrix} -1\\2\\1\\0 \end{bmatrix} + a_2 \begin{bmatrix} 1\\0\\1\\0 \end{bmatrix} + a_3 \begin{bmatrix} -1\\-1\\1\\1 \end{bmatrix} + a_4 \begin{bmatrix} 1\\1\\1\\2 \end{bmatrix} = \begin{bmatrix} 0\\0\\0\\0 \end{bmatrix}$$

then

$$-a_1 + a_2 - a_3 + a_4 = 0$$
$$2a_1 - a_3 + a_4 = 0$$
$$a_1 + a_2 + a_3 + a_4 = 0$$
$$a_3 + 2a_4 = 0.$$

The adding twice the first equation to the second and adding the first equation to the third gives

$$-a_1 + a_2 - a_3 + a_4 = 0$$
$$2a_2 - 3a_3 + 3a_4 = 0$$
$$2a_2 + 2a_4 = 0$$
$$a_3 + 2a_4 = 0.$$

Subtracting the second equation from the third gives

$$-a_1 + a_2 - a_3 + a_4 = 0$$
$$2a_2 - 3a_3 + 3a_4 = 0$$
$$3a_3 - a_4 = 0$$
$$a_3 + 2a_4 = 0.$$

Finally, subtracting $\frac{1}{3}$ times the third equation from the fourth gives

$$-a_1 + a_2 - a_3 + a_4 = 0$$
$$2a_2 - 3a_3 + 3a_4 = 0$$
$$3a_3 - a_4 = 0$$
$$\frac{7}{3}a_4 = 0.$$

Thus $a_4 = a_3 = a_2 = a_1 = 0$ so the set is linearly independent.

#5 (a) Let $W_1 = \{f(x) \in \mathcal{P}_3 | f(1) = f(2)\}$. Is W_1 a subspace of \mathcal{P}_3 ? Why or why not? (b) Let $W_2 = \{f(x) \in \mathcal{P}_3 | f(1) = 2\}$. Is W_2 a subspace of \mathcal{P}_3 ? Why or why not?

Solutions: (a) Clearly the zero function is in W_1 . If $f, g \in W_1$, then (f + g)(1) = f(1) + g(1) = f(2) + g(2) = (f + g)(2) so $f + g \in W_1$. Also, if $a \in F$ we have (af)(1) = af(1) = af(2) = (af)(2) so $af \in W_1$. Thus W_1 is a subspace.

(b) The zero function is not in W_2 and so W_2 is not a subspace.

#6 Let V and W be vector spaces and $v_1, ..., v_n \in V$. State the definition of each of the following terms:

- (a) The span of $\{v_1, ..., v_n\}$
- (b) $\{v_1, ..., v_n\}$ is linearly independent
- (c) A basis of V.
- (d) The dimension of V
- (e) A linear transformation from V to W.

Solution: (a) Let V be a vector space over F. $Span\{v_1,...,v_n\} = \{a_1v_1+...+a_nv_n|a_1,...,a_n \in F\}$.

- (b) $\{v_1, ..., v_n\}$ is linearly independent if whenever $a_1v_1 + ... + a_nv_n = 0$ we must have $a_1 = ... = a_n = 0$.
- (c) A subset S of a vector space V is a basis for V if it spans V and is linearly independent.
 - (d) The dimension of V is the number of elements in any basis for V.
- (e) A function T from V to W (which are vector spaces over a field F) is a linear transformation if, for every $v_1, v_2 \in V$ and every $a \in F$ we have $T(v_1 + v_2) = T(v_1) + T(v_2)$ and $T(av_1) = aT(V_1)$.
- #7 (a) Is F^3 isomorphic to $M_{2\times 2}(F)$? Why or why not?
 - (b) Is F^3 isomorphic to $\{A \in M_{2\times 2}(F) | A = A^t\}$? Why or why not?
 - (c) Is F^2 isomorphic to $\{A \in M_{2\times 2}(F) | A = A^t\}$? Why or why not?
 - (d) Is F^2 isomorphic to $\{A \in M_{2\times 2}(F) | A = -A^t\}$? Why or why not?

Solution: (a) No, since $dim(F^3) = 3$ and $dim(M_{2\times 2}(F)) = 4$.

(b) $\{A \in M_{2\times 2}(F) | A = A^t\}$ has basis

$$\{\begin{bmatrix}1 & 0\\0 & 0\end{bmatrix},\begin{bmatrix}0 & 1\\1 & 0\end{bmatrix},\begin{bmatrix}0 & 0\\0 & 1\end{bmatrix}\}$$

and hence has dimension 3. Thus the two spaces have the same dimension and so are isomorphic.

- (c) No, as the two spaces have different dimensions.
- (d) First assume that the characteristic of the field F is not 2, i.e., assume that $2 \neq 0$ in F. Then $\{A \in M_{2\times 2}(F) | A = -A^t\}$ is 1-dimensional with basis $\{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} .\}$ Hence the two spaces have different dimensions and so are not isomorphic. If F has characteristic 2 then $-A^t = A^t$ so this is the same as part (b) (and the two spaces are not isomorphic).

#8 Let $V = \mathbf{R}^3$, let $\{e_1, e_2, e_3\}$ be the standard basis, and let $\beta = \{f_1, f_2, f_3\}$ be the dual basis. Define $g \in \mathcal{L}(V, \mathbf{R})$ by

$$g(\begin{bmatrix} r \\ s \\ t \end{bmatrix}) = r + 2s - 3t.$$

Express g as a linear combination of elements of β .

Solution: Write

$$g = a_1 f_1 + a_2 f_2 + a_3 f_3.$$

Recall that $f_i(e_j) = 0$ if $i \neq j$ and that $f_i(e_i) = 1$. Then we have

$$1 = g(e_1) = a_1 f_1(e_1) + a_2 f_2(e_1) + a_3 f_3(e_1) = a_1,$$

$$2 = g(e_2) = a_1 f_1(e_2) + a_2 f_2(e_2) + a_3 f_3(e_2) = a_2,$$

$$-3 = g(e_3) = a_1 f_1(e_3) + a_2 f_2(e_3) + a_3 f_3(e_3) = a_3.$$

Thus $g = f_1 + 2f_2 - 3f_3$.

#9 Let

$$A = \begin{bmatrix} 3 & -1 & 2 & 2 \\ 1 & 0 & 0 & 1 \\ -1 & 2 & 2 & 4 \end{bmatrix},$$

$$B = \begin{bmatrix} 4 & -1 & 2 & 3 \\ 1 & 0 & 0 & 1 \\ -1 & 2 & 2 & 4 \end{bmatrix},$$

and

$$C = \begin{bmatrix} 3 & 5 & 2 & 2 \\ 1 & 2 & 0 & 1 \\ -1 & 0 & 2 & 4 \end{bmatrix}.$$

Find elementary matrices P and Q such that PA = B and AQ = C.

Solution: The matrix B is obtained from A by adding the second row to the first row. We obtain P by performing this same row operation on the (3 by 3) identity matrix. Thus

$$P = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

The matrix \vec{C} is obtained from A by adding twice the first column to the second column. We obtain Q by performing this same column operation on the (4 by 4) identity matrix.

Thus
$$Q = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
.

#10 Suppose $V_1, ..., V_6$ are vector spaces with

$$V_1 \subseteq V_2 \subseteq V_3 \subseteq V_4 \subseteq V_5 \subseteq V_6$$

and $dim(V_6) = 4$. Prove that $V_i = V_{i+1}$ for some $i, 1 \le i \le 5$.

Solution: We have

$$0 \le dim(V_1) \le dim(V_2) \le dim(V_3) \le dim(V_4) \le dim(V_5) \le dim(V_6) = 4.$$

Since there are only five possibilities (0,1,2,3,4) for the six integers $dim(V_1),...,dim(V_6)$ we must have $dim(V_i) = dim(V_{i+1})$ for some $i, 1 \leq i \leq 5$. Since $V_i \subseteq V_{i+1}$ this implies $V_i = V_{i+1}.$

#11 Let
$$P = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$
. Find P^{-1} . Show your work.

Solution:

$$\begin{bmatrix}
1 & 2 & 2 & 1 & 0 & 0 \\
2 & 3 & 1 & 0 & 1 & 0 \\
1 & 1 & 1 & 0 & 0 & 1
\end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 & -1 & -3 & 2 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -1 & -3 & 2 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & -2 & 1 & 1 \\ 0 & -1 & 0 & -1 & 0 & 1 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & -2 & 1 & 1 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}.$$

Therefore

$$P^{-1} = \begin{bmatrix} -2 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & -1 & 1 \end{bmatrix}.$$